


Lezione 15

(M, g) varietà pseudo-Riemanniana

↳ distanza (Riemanniano) solo nel caso

↳ forma volume $\omega = \sqrt{|\det g_{ij}|} dx^1 \wedge \dots \wedge dx^n$

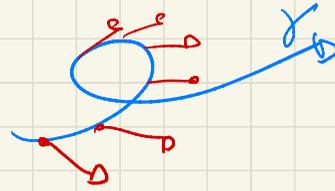
↳ g_{ij} prod. scalare $\Rightarrow \|v\| = \sqrt{|g_{ij} v^i v^j|}$
 $\underbrace{\hspace{10em}}_{g(v,v)}$

↳ $L(\gamma)$ lunghezza di curva γ

↳ ∇ connessione (di Levi-Civita)

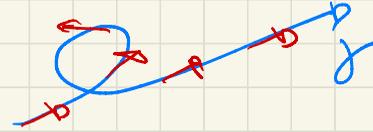
unica ∇ simmetrica e compatibile con g
 $\Gamma_{ij}^k = \Gamma_{ji}^k$

↳ Trasporto parallelo



↳ geodetica

$$\ddot{x} + \dot{x}^i \dot{x}^j \Gamma_{ij}^k e^k = 0$$



↳ curvatura

Oss: $\ddot{x} + \dot{x}^i \dot{x}^j \Gamma_{ij}^k e^k = 0$ $\ddot{x}^k + \dot{x}^i \dot{x}^j \Gamma_{ij}^k = 0$

n equazioni differenziali al II ordine $k=1, \dots, n$

$$\ddot{x}^k(t) + \dot{x}^i(t) \dot{x}^j(t) \Gamma_{ij}^k(x(t)) = 0$$

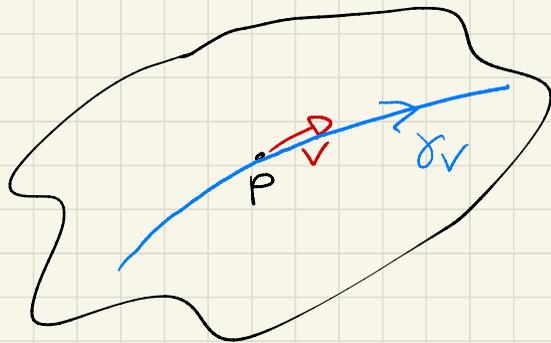
NON È LINEARE $\Rightarrow x(t)$ può non esistere

$\exists!$ locale : $\exists!$ $x(t)$ se fisso $x(t_0), \dot{x}(t_0)$

LOCALMENTE

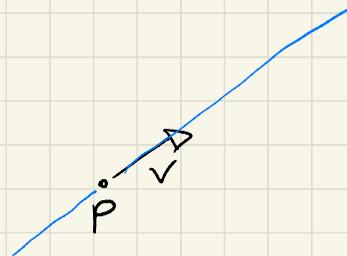
$\forall t \in \mathbb{R}$

Cor: (M, ∇) $\forall p \in M, \forall v \in T_p M \exists!$ geodetica
 maximale



$$\begin{aligned} \gamma_v: I_v &\rightarrow M \quad \text{t.c.} \\ \gamma_v(0) &= p \quad I_v \subseteq \mathbb{R} \\ \dot{\gamma}_v(0) &= v \end{aligned}$$

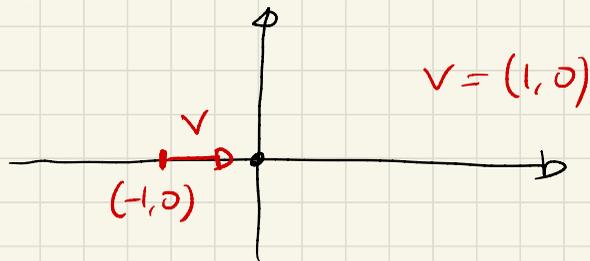
Es: $M = \mathbb{R}^2, \nabla^E$



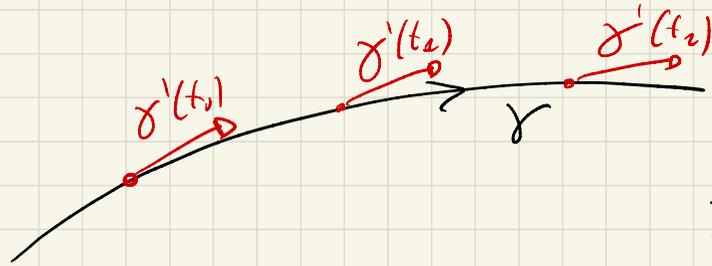
$$\gamma_v(t) = p + tv$$

$$I_v = \mathbb{R}$$

$M = \mathbb{R}^2 - \{0\}, \nabla^E$



Oss: Se γ geodetica, allora $\|\gamma'(t)\| = \text{cost}$



γ' è parallelo

\Downarrow

$\gamma'(t)$ è ottenuto da $\gamma'(t_0)$

per trasporto parallelo lungo γ ,

che è isometria perché $g \in \nabla$

sono compatibili

Quindi ci sono 3 tipi di geodetiche:

TEMPO, SPAZIO E LUCE

(anche $\langle \gamma'(t), \gamma'(t) \rangle$ è costante)

Oss: Se $\gamma(t)$ è geodetica e $c > 0$

allora anche $\eta(t) = \gamma(ct)$

$$\ddot{x}^k + \underbrace{\dot{x}^i \dot{x}^j}_{c \cdot c} \Gamma_{ij}^k = 0$$

$x(t)$ è soluzione $\Rightarrow x(ct)$ è soluz.

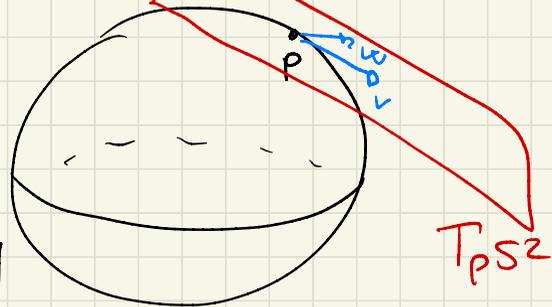
Sottovarietà pseud-Riemanniana

$$N \subseteq M$$

$$(M, g) \dashrightarrow g^N \text{ su } N$$

$$g^N(p) = g(p) \Big|_{T_p N \subseteq T_p M}$$

Es: $S^2 \subseteq \mathbb{R}^3$



Che relazione c'è tra ∇^N e ∇^M ?

$$(M, g) \dashrightarrow \nabla^M$$

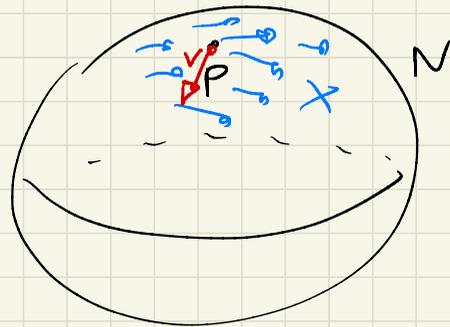
$$\begin{array}{c} \vdots \\ \nabla^M \\ \vdots \\ (N, g^N) \dashrightarrow \nabla^N \end{array}$$

Prop: $\nabla^N = \pi_* \nabla^M$ cioè: M

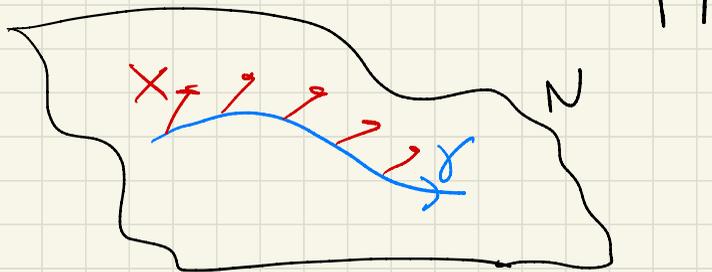
$T_p N \ni \nabla_v^N X = \pi_* \left(\nabla_v^M X \right) \in T_p M$

$\pi: T_p M \rightarrow T_p N$

proiezione ortogonale



Cor:



X è parallelo rispetto a $N \iff \nabla_{\gamma'(t)}^N X = 0 \quad \forall t$

$\iff \nabla_{\gamma'(t)}^M X \perp T_{\gamma(t)} N \quad \forall t$

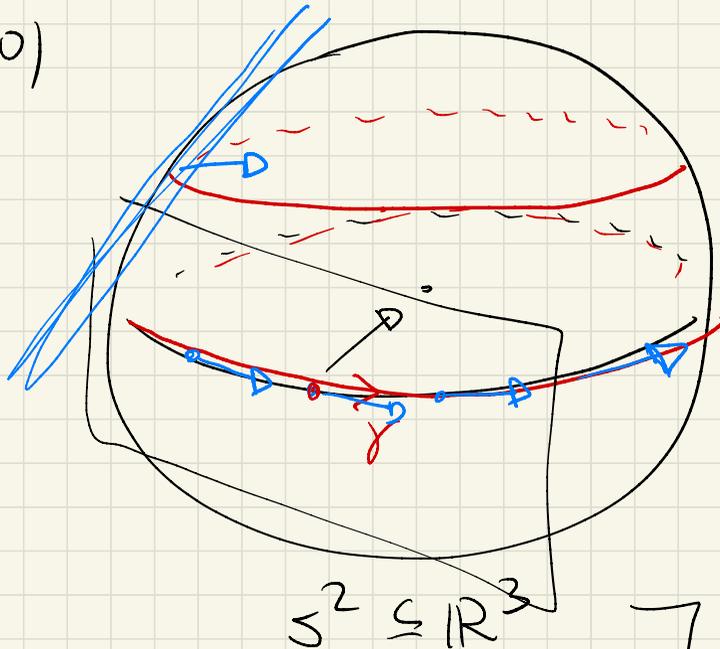
$$\gamma''(t) = (-\cos t, -\sin t, 0)$$

$$\gamma(t) = (\cos t, \sin t, 0)$$

$$\gamma'(t) = (-\sin t, \cos t, 0)$$

γ è geodetica in S^2

perché vale il seguente



Con: $N \subseteq M$ $\gamma: I \rightarrow N$ è geodetica

$$\Leftrightarrow \forall t \in I$$

$$\nabla_{\dot{\gamma}(t)}^M \dot{\gamma}(t) \perp T_{\gamma(t)} M$$

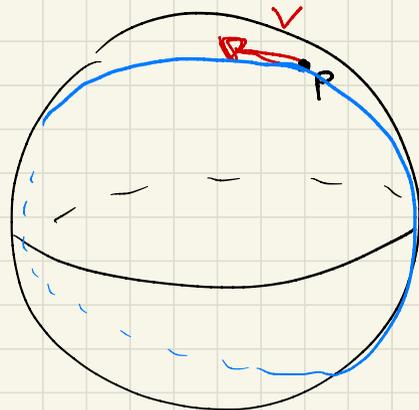
Con: $N \subseteq \mathbb{R}^3$ surface $\gamma: I \rightarrow N$ curve

$$\gamma \text{ geod.} \iff \gamma''(t) \perp T_{\gamma(t)} M$$

Ex: $p \in S^2$ $\|p\| = 1$

$$v \in T_p S^2 = p^\perp$$

$$\|v\| = 1$$



$$\gamma_v(t) = p \cos t + v \sin t$$

- $\gamma_v(t) \in S^2 \quad \forall t \quad \|\gamma_v(t)\| = 1$

- $\dot{\gamma}_v(t) = -\gamma_v(t) \perp (\gamma_v(t)^\perp)$

Ex: $p \in I^2 \subseteq \mathbb{R}^{2,1}$

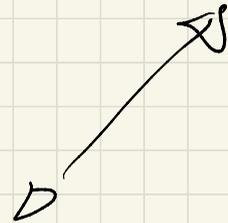
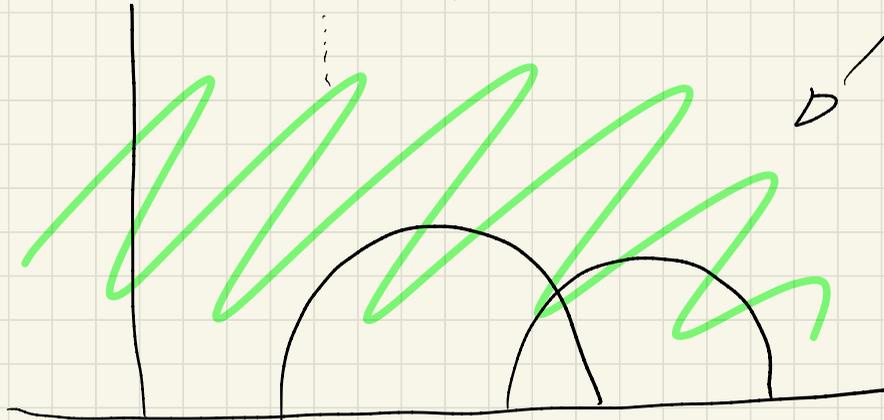
$$v \in T_p I^2$$

$$\|v\| = 1$$

$$\gamma_v(t) = p \cosh t + v \sinh t$$

si ottiene in modo simile

$$T_p \mathbb{I}^2 = p^\perp$$



CURVATURA

$$(M, \nabla) \quad \nabla \dashrightarrow T \text{ TORSIONE} \quad (1, 2)$$

$T \equiv 0$ (di solito)

$$T(p) = \nabla_X Y - \nabla_Y X - [X, Y]$$

Def: **TENSORE DI RIEMANN**

(1, 3)

$$T^i_{jk} = \Gamma^i_{jk} - \Gamma^i_{kj}$$

$$(M, \nabla)$$

$$\forall p \in M, \quad \forall u, v, w \in T_p M$$

$$\begin{array}{ccc} \downarrow & \downarrow & \downarrow \\ X & Y & Z \end{array}$$

estensioni arbitrarie

$$R(p)(u, v, w) = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$$

$\nabla_v w$
non ha senso

$\nabla_u \nabla_v z$ non ha senso
vettore

$\nabla_u \nabla_y z$ ha senso

Tes: Non dipende dalle estensioni

In arte $R_{ijk}^l = \frac{\partial \Gamma_{jk}^l}{\partial x^i} - \frac{\partial \Gamma_{ik}^l}{\partial x^j} + \Gamma_{im}^l \Gamma_{jk}^m - \Gamma_{jm}^l \Gamma_{ik}^m$

n^4

$$R(u, v, w)^l = R_{ijk}^l u^i v^j w^k$$

$$R(u, v, w) = R_{ijk}^l u^i v^j w^k e_l$$

Simmetrie: riducono i grad. di libertà da n^4 a ...

$n=2$: $2^4 \rightarrow 1$ R_{121}^2 $n=4$: $4^4 \rightarrow 20$

$n=3$: $3^4 \rightarrow 6$

$$w' = w + t^2 z + o(t^2)$$

Tensore di Ricci

$$R_{ijk}{}^l$$

(1,3)

→

$$R_{ij} = R_{kij}{}^k$$

(0,2)

contrazione

$$A^i{}_j$$

(1,1)

→

$$A^i{}_i = \text{tr} A$$

(0,0)

Teo: $R_{ij} = R_{ji}$ \bar{e} simmetrico

COMPARE NELL'EQ. DI CAMPO DI EINSTEIN

g_{ij} tensore metrico

T_{ij} tensore energia-impulso

CURVATURA SCALARE

$$R_{ij}$$

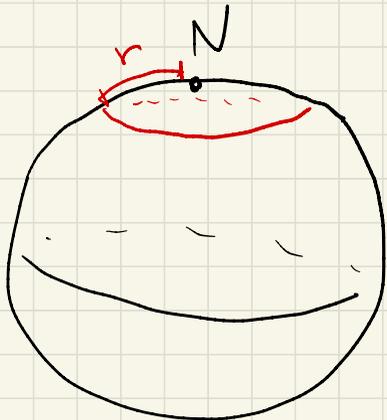
$$R_i^j = R_{ik} g^{kj}$$

$$R = R_i^i = R_{ik} g^{ki}$$



$$B(p, r) = \{q \in M \mid d(p, q) < r\}$$

$$\text{Vol}(B(p, r)) = \underset{\substack{\uparrow \\ \text{Euclides}}}{V_r^n} \left(1 - \frac{1}{6(n+2)} R r^2 + o(r^2) \right)$$



$$B(N, r) < \pi r^2$$

$$R = 1$$

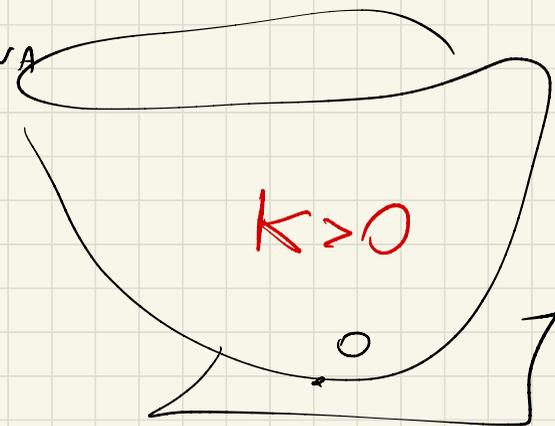
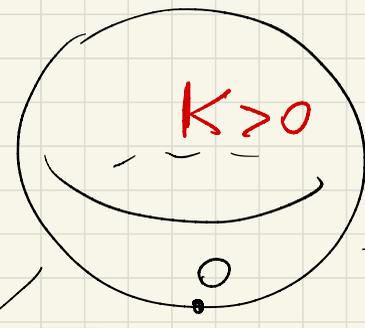
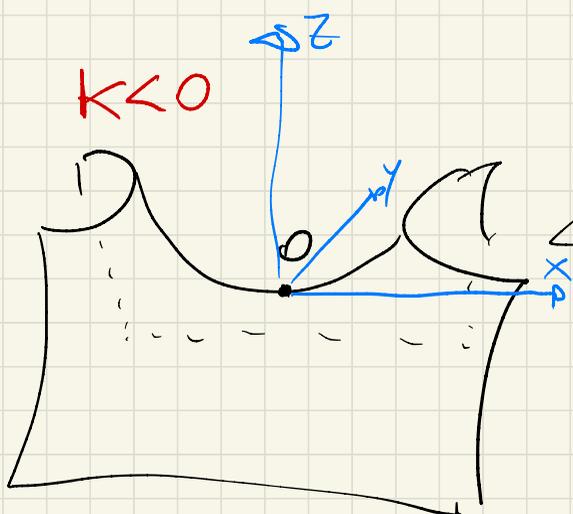
$$S^n \quad R \equiv 1$$

$$\mathbb{R}^n \quad R \equiv 0$$

$$H^n \quad R \equiv -1$$

CURVATURA GAUSSIANA

$S \subseteq \mathbb{R}^3$ superficie



$$z = x^2 - y^2$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$z = \frac{1}{2}(x^2 + y^2) + o \dots$$

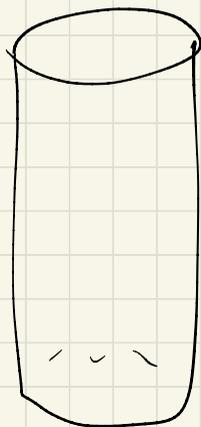
S è loc. grafico di f

$$\begin{pmatrix} -\lambda & 0 \\ 0 & -\lambda \end{pmatrix} \quad \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} \quad \lambda > 0$$

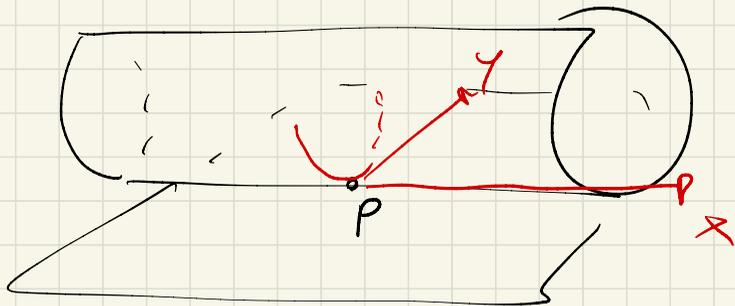
scalar $R = 2K$ gaussian

$$f(x, y) = \vec{x} \cdot \text{Hess} f \cdot y + o(x^2 + y^2)$$

$$K = \det \text{Hess} f$$



$$K=0$$



$$f(x, y) = \lambda y^2$$

$$\text{Hess} f = \begin{pmatrix} \lambda & 0 \\ 0 & 0 \end{pmatrix}$$